

# **Rotating System RS130** Detecting longitudinal defects at large diameters



# First rate products through reliable eddy current testing

Today's rod, bar and wire industry requires testing procedures that recognize longitudinal surface defects of small depth.

The eddy current inspection method suits these needs particularly well, since it shows a high sensitivity to surface defects.

A special eddy current sensor, the rotating system spirally scans the

surface of the test material for even the tiniest longitudinal cracks and tears – depending on the surface conditions. Due to its high resolution and transverse movement across the crack (rather than along it), the rotating system finds defects sometimes missed by conventional encircling coils.

- Inspection before and after production
- High sensitivity
- Range of probe types available
- Lift-off compensation between probe and oval test piece
- Robust design for rigorous industrial environment
- Userfriendly operation
- Easy service

# Robust, userfriendly, and easy to maintain

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The inspection unit consists of a sleeve shaft construction with a robust, industrial spindle bearing, a non-contact signal transmitter and a heavy-duty probe head.

#### **Convenient service**

The centering unit lifts up and away, allowing frontal access for diameter adjustment, exchange of probes and service.

# 

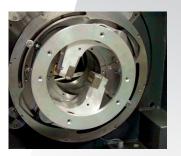
Adjustment of centering diameter

Emergency-stop safety switch

# Precise test piece guidance

Built-in centering The solidly-built, 3-roller centering guarantees precise guidance to an accuracy of 0.1 mm. It is located on both sides of the system and is externally adjustable.

Auxiliary guide sleeves More accurate and narrow guidance is required for small diameter material to prevent test material from hitting the sensors. Special guide sleeves attach internally at the infeed and/or outfeed for this purpose.



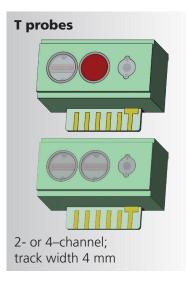
## **Testing head**

The testing head features a plate with probes on spring mounted probe arms. The diameter can be changed quickly and the probes can be replaced easily if needed.

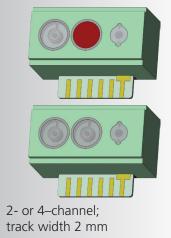
# **Eddy current probes**

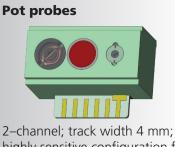
The exchangeable probes are well protected and easily replaced. The probe case holds 1 or 2 differential probes and a lift-off probe.

Depending on the material to be tested a range of probe types can be used with the RS130:



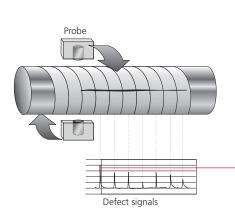
# **Dual core probes**



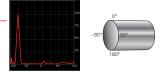


highly sensitive configuration for finding longitudinal defects

# How the rotating system works

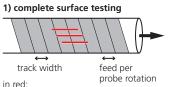


The rotating system scans the test piece in a helical pattern. Every time a probe crosses a crack, it generates a defect signal. In doing so, the rotating system produces a great number of consecutive signals that identify the flaw as a crack. The defect signals appear on the screen as they occur. An angular display shows the position of the defect on the circumference of the test piece.



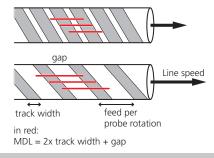
# **Minimum defect length**

# and production speed



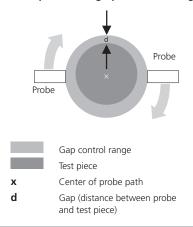
minimum defect length (MDL) = 2x track width

#### 2) non-complete surface testing



Lift-off compensation

The option for high precision testing



In complete testing, the feed per revolution corresponds exactly to the probe width. In order to be able to definitely(!) detect a defect, it must at least cover one probe track completely (see red defect markings). The minimum defect length MDL in complete surface testing can therefore not be smaller, than twice the probe width.

In order to be able to definitely detect a defect during a non-complete surface testing, it also must at least cover one probe track completely (see red defect markings). Accordingly, MDL is enlarged to 2x track width plus 1x gap width.

The maximum possible production speed vmax for a specific MDL is calculated as follows:

vmax [m/s] = rpm x number of probes x (track width + gap) / 60000

(gap = MDL minus 2x track width) vmax [m/s] = rpm x number of probes x (MDL minus track width) / 60000

The optional lift-off compensation corrects distorted signals that arise from a varying gap between the probe and test piece. The smaller the gap, the larger the defect signal. If the test pieces are off-center, defects of the same size produce different signal amplitudes, resulting in inaccuracies in the defect evaluation. The lift-off compensation system corrects this effect and ensures reliable test results.

# **Reliable semi-finished product testing**

# Production speed and minimum defect length

		Complete partial surface testing											
			minimum defect length in mm										
2 T–Probes	Order No.		8	10	12	14	16	18	20	25	30	35	40
with track width 4 mm	LAB 6215ND LAB 6217ND LAB 6219ND	RPM	max. production speed in m/s										
		1500	0.2	0.3	0.4	0.5	0.6	0.7	0.8	1.05	1.3	1.55	1.8
		3000	0.4	0.6	0.8	1.0	1.2	1.4	1.6	2.1	2.6	3.1	3.6
			minimum defect length in mm										
4 T–Probes	al LAB 6216ND th LAB 6246ND		24	26	28	30	32	34	36	38	40	45	50
with total track width		RPM	max. production speed in m/s										
		1500	0.6	0.7	0.8	0.9	1.0	1.1	1.2	1.3	1.4	1.65	1.9
12 mm		3000	1.2	1.4	1.6	1.8	2.0	2.2	2.4	2.6	2.8	3.3	3.8
	Production speed (m/s) = RPM x Number of probes x (Minimum defect length (mm) – Track width (mm)) / 60,000												

# **Technical data RS130**

# **Testing material**

- Tubing, pipe, bar, wire
- Ferrous, nonferrous and austenitic metals
- Size range: Ø 20-130 mm (3/4–5 1/8")
- Temperature of inspected material: -20° -70°C

### Weights

• RS130 650 kg (1430 lb); control cabinet 18 kg (40 lb)

# **Eddy current instrument**

• EDDYCHEK<sup>®</sup> 5; EDDYCHEK<sup>®</sup> 610

#### **Production line**

- Continuous production with cut-off
- Continuous production without cut-off (e.g. drawing line)
- Testing of cut lengths (offline)

# **Defect resolution**

- Min. defect length see table depends on production speed and probe
- Min. defect depth: 0.05 mm (0.0012") depends on surface conditions

#### **Probes**

- 2 or 4 differential probes on two test heads
- Optional lift-off compensation; max. lift-off: 2 mm
- Probe type dependent on throughput and surface

# **Guidance system/Centering**

- Built-in roller guide system
- Bushings for diameters < 30 mm optional

# **Rotations per minute**

• 1500 or 3000 RPM

# Motor and power supply

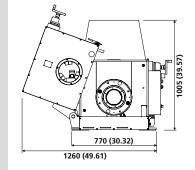
- Asynchron. 4-pole switchable motor with mechanical brake
- 400V, 50/60 Hz, 2.5kVA. Different voltages possible with isolating transformer
- 115/230 V, 0.5 kW, 50/60 Hz

# Demagnetization

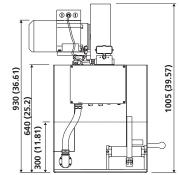
• Recommended for material with >10 A/cm

### PLC

• Signal output for system control automatization available



Dimensions in mm (in)



# System configuration



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